Damascus University Higher Institute of Earthquake Studies and Researches

### **Continuum Mechanics- Elasticity and Plasticity**

**Lec.07** 

### **Linear Stress-Strain Relation Problems**

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#### Problem 1:

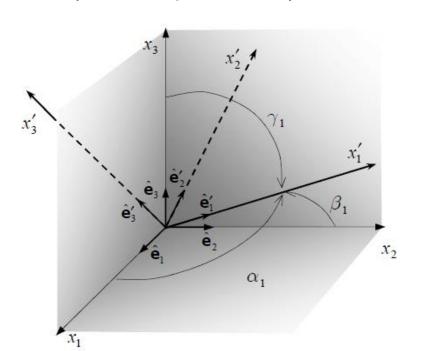
تعطى الحالة الإجهادية في نقطة في وسط مستمر بالمركبات المعرفة من خلال تنسور كوتشي للإجهادات كما يلي:

- $x_{1}, x_{2}, x_{3}$  في نظام جديد  $\sigma$  الإجهادات  $\sigma$  في نظام جديد الإجهادات  $\sigma$ 
  - $\sigma$  أحسب اللامتغيرات الأساسية للإجهاد.
  - 3- أحسب الإجهادات الرئيسية والإتجاهات الرئيسية.

$$\sigma_{ij} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \text{pa}$$

$$a_{ij} = \frac{1}{5} \begin{bmatrix} 3 & 0 & -4 \\ 0 & 5 & 0 \\ 4 & 0 & 3 \end{bmatrix}$$

where  $a_{11} = \cos \alpha_1$   $a_{12} = \cos \beta_1$   $a_{13} = \cos \gamma_1$  $\vdots$ 



1- the transformation law for the components of a second order tensor is given by:

$$\sigma'_{ij} = a_{ik} a_{jl} \sigma_{kl} \xrightarrow{\text{Matrix form}} \sigma' = \mathcal{A} \sigma \mathcal{A}^{T}$$

$$\sigma'_{ij} = \frac{1}{5^{2}} \begin{bmatrix} 3 & 0 & -4 \\ 0 & 5 & 0 \\ 4 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 2 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 3 & 0 & 4 \\ 0 & 5 & 0 \\ -4 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 2 & 0.6 & 0 \\ 0.6 & 2 & 0.8 \\ 0 & 0.8 & 2 \end{bmatrix}$$

$$\sigma' = \mathcal{A} \sigma \mathcal{A}^{T}$$

$$\sigma'_{ij} = \frac{1}{5^{2}} \begin{bmatrix} 3 & 0 & -4 \\ 0 & 5 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 3 & 0 & 4 \\ 0 & 5 & 0 \\ -4 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 2 & 0.6 & 0 \\ 0.6 & 2 & 0.8 \\ 0 & 0.8 & 2 \end{bmatrix}$$

$$\sigma' = \mathcal{A} \sigma \mathcal{A}^{T}$$

$$\sigma_{ij} = \frac{1}{5^{2}} \begin{bmatrix} 3 & 0 & -4 \\ 0 & 3 & 3 \end{bmatrix} \begin{bmatrix} 3 & 0 & 4 \\ 0 & 0 & 3 \end{bmatrix} =$$

2- The principal invariants of the Cauchy stress tensor can be calculated as follows: law for the components of a second order tensor is given by:

$$\begin{split} I_{\sigma} &= \text{Tr}(\boldsymbol{\sigma}) = \sigma_{ii} = \sigma_{11} + \sigma_{22} + \sigma_{33} \\ II_{\sigma} &= \frac{1}{2} \Big[ (\text{Tr}\boldsymbol{\sigma})^2 - \text{Tr}(\boldsymbol{\sigma}^2) \Big] = \frac{1}{2} \Big( \sigma_{ii} \sigma_{jj} - \sigma_{ij} \sigma_{ij} \Big) \\ &= \sigma_{11} \sigma_{22} + \sigma_{11} \sigma_{33} + \sigma_{33} \sigma_{22} - \sigma_{12}^2 - \sigma_{13}^2 - \sigma_{23}^2 \\ III_{\sigma} &= \det(\boldsymbol{\sigma}) = \epsilon_{ijk} \sigma_{i1} \sigma_{j2} \sigma_{k3} = \frac{1}{6} \Big( \sigma_{ii} \sigma_{jj} \sigma_{kk} - 3\sigma_{ii} \sigma_{jk} \sigma_{jk} + 2\sigma_{ij} \sigma_{jk} \sigma_{ki} \Big) \\ &= \sigma_{11} \sigma_{22} \sigma_{33} + 2\sigma_{12} \sigma_{23} \sigma_{13} - \sigma_{11} \sigma_{23}^2 - \sigma_{22} \sigma_{13}^2 - \sigma_{33} \sigma_{12}^2 \end{split}$$

By substituting the values of  $\sigma_{ij}$  for those in the proposed problem we obtain:

$$I_{\sigma} = 6$$
 ;  $II_{\sigma} = \begin{vmatrix} 2 & 0 \\ 0 & 2 \end{vmatrix} + \begin{vmatrix} 2 & 0 \\ 0 & 2 \end{vmatrix} + \begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix} = 11$  ;  $III_{\sigma} = 6$ 

c) The principal stresses  $(\sigma_i)$  and principal directions  $(\hat{\mathbf{n}}^{(i)})$  are obtained by solving the following set of equations:

$$\begin{bmatrix} 2-\sigma & 1 & 0 \\ 1 & 2-\sigma & 0 \\ 0 & 0 & 2-\sigma \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

To obtain the nontrivial solutions of  $\hat{\mathbf{n}}^{(t)}$  we have to solve the characteristic determinant, which is a cubic equation for the unknown magnitude  $\sigma$ :

$$|\sigma_{ij} - \sigma \delta_{ij}| = 0 \implies \sigma^3 - I_{\sigma} \sigma^2 + II_{\sigma} \sigma - III_{\sigma} = 0$$

However, if we look at the format of the Cauchy stress tensor components, we can notice that we already have one solution as in the  $x_3$ -direction the tangential components are equal to zero, then:

$$\sigma_3 = 2 \xrightarrow{\text{Principal direction}} \quad n_1^{(3)} = n_2^{(3)} = 0, \quad n_3^{(3)} = 1$$

c) The principal stresses  $(\sigma_i)$  and principal directions  $(\hat{\mathbf{n}}^{(i)})$  are obtained by solving the following set of equations:

To obtain the other two eigenvalues, one only need solve:

$$\begin{vmatrix} 2-\sigma & 1 \\ 1 & 2-\sigma \end{vmatrix} = (2-\sigma)^2 - 1 = 0 \implies \begin{cases} \sigma_1 = 1 \\ \sigma_2 = 3 \end{cases}$$

Then we can express the Cauchy stress tensor components in the principal space as:

$$\sigma_{ij}'' = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix} Pa$$

c) The principal stresses  $(\sigma_i)$  and principal directions  $(\hat{\mathbf{n}}^{(i)})$  are obtained by solving the following set of equations:

Additionally, the principal direction associated with  $\sigma_1 = 1$  is calculated as follows:

$$\begin{bmatrix} 2-1 & 1 & 0 \\ 1 & 2-1 & 0 \\ 0 & 0 & 2-1 \end{bmatrix} \begin{bmatrix} n_1^{(1)} \\ n_2^{(1)} \\ n_3^{(1)} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} n_1^{(1)} + n_2^{(1)} = 0 \\ n_1^{(1)} + n_2^{(1)} = 0 \\ \end{bmatrix} \Rightarrow n_1^{(1)} = -n_2^{(1)}$$

with  $n_3^{(l)} = 0$  and by using the condition  $n_1^{(l)^2} + n_2^{(l)^2} = 1$  we obtain:

$$n_1^{(1)} = -n_2^{(1)} = \frac{1}{\sqrt{2}}$$
 then  $\hat{n}_i^{(1)} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} & 0 \end{bmatrix}$ 

Since  $\sigma$  is a symmetric tensor, the principal space is formed by an orthogonal basis, so, it is valid that:

$$\hat{\mathbf{n}}^{(1)} \wedge \hat{\mathbf{n}}^{(2)} = \hat{\mathbf{n}}^{(3)}$$
;  $\hat{\mathbf{n}}^{(2)} \wedge \hat{\mathbf{n}}^{(3)} = \hat{\mathbf{n}}^{(1)}$ ;  $\hat{\mathbf{n}}^{(3)} \wedge \hat{\mathbf{n}}^{(1)} = \hat{\mathbf{n}}^{(2)}$ 

c) The principal stresses  $(\sigma_i)$  and principal directions  $(\hat{\mathbf{n}}^{(i)})$  are obtained by solving the following set of equations:

Thus, the second principal direction can be obtained by the cross product between  $\hat{\mathbf{n}}^{(3)}$  and  $\hat{\mathbf{n}}^{(1)}$ , i.e.:

$$\hat{\mathbf{n}}^{(2)} = \hat{\mathbf{n}}^{(3)} \wedge \hat{\mathbf{n}}^{(1)} = \begin{vmatrix} \hat{\mathbf{e}}_1 & \hat{\mathbf{e}}_2 & \hat{\mathbf{e}}_3 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} & 0 \end{vmatrix} = \frac{1}{\sqrt{2}} \hat{\mathbf{e}}_1 + \frac{1}{\sqrt{2}} \hat{\mathbf{e}}_2$$

which can also be checked by the following analysis:

The Principal direction associated with  $\sigma_2 = 3$ :

$$\begin{bmatrix} 2-3 & 1 & 0 \\ 1 & 2-3 & 0 \\ 0 & 0 & 2-3 \end{bmatrix} \begin{bmatrix} n_1^{(2)} \\ n_2^{(2)} \\ n_3^{(2)} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} -n_1^{(2)} + n_2^{(2)} = 0 \\ n_1^{(2)} - n_2^{(2)} = 0 \end{cases} \Rightarrow n_1^{(2)} = n_2^{(2)}$$

With  $n_3^{(3)} = 0$  and using the condition  $n_1^{(3)2} + n_2^{(3)2} = 1$  we obtain:

$$n_1^{(2)} = n_2^{(2)} = \frac{1}{\sqrt{2}}$$
 then  $\hat{n}_i^{(2)} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{bmatrix}$ 

As we have seen in Chapter 1, the eigenvectors of a symmetric tensor form the transformation matrix  $\mathcal{D}$ , from the original system to the principal space, i.e.  $\sigma'' = \mathcal{D} \sigma \mathcal{D}^T$ , thus:

$$\begin{bmatrix} \sigma_1 = 1 & 0 & 0 \\ 0 & \sigma_2 = 3 & 0 \\ 0 & 0 & \sigma_3 = 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

### Problem 2:

At point P the Cauchy stress tensor components are:

$$\sigma_{ij} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 1 \end{bmatrix} MPa$$

#### Find:

- a) the traction vector  $\vec{\mathbf{t}}$  related to the plane which is normal to the  $x_1$ -axis;
- b) the traction vector  $\vec{\mathbf{t}}$  associated with the plane whose normal is (1,-1,2);
- c) the traction vector  $\vec{\mathbf{t}}$  associated with the plane parallel to the plane  $2x_1 2x_2 x_3 = 0$ ;
- d) the principal stress at the point P;
- e) the principal directions of σ at the point P.

a) In this case, the unit vector is (1,0,0). Then, the traction vector is given by:

$$\mathbf{t}_{i}^{(\hat{\mathbf{n}})} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

b) The unit vector associated with the direction (1,-1,2) is:

$$\hat{\mathbf{n}}_i = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

thus,

$$\mathbf{t}_{i}^{(\hat{\mathbf{n}})} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \frac{1}{\sqrt{6}} \begin{bmatrix} 5 \\ 10 \\ -1 \end{bmatrix}$$

#### Problem 2:

Solution:

c)

$$\hat{\mathbf{n}}_{i} = \frac{1}{3} \begin{bmatrix} 2 \\ -2 \\ -1 \end{bmatrix} \Rightarrow \mathbf{t}_{i}^{(\hat{\mathbf{n}})} = \frac{1}{3} \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ -2 \\ -1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} -5 \\ -10 \\ -7 \end{bmatrix}$$

d) Solving the characteristic determinant

$$\begin{vmatrix}
 1 - \sigma & 2 & 3 \\
 2 & 4 - \sigma & 6 \\
 3 & 6 & 1 - \sigma
 \end{vmatrix} = 0$$

we obtain:

$$\sigma_1 = 10$$
;  $\sigma_2 = 0$ ;  $\sigma_3 = -4$ 

#### Problem 2:

#### Solution:

e) The principal directions are:

Associated with  $\sigma_1 = 10$ 

$$\begin{cases} -9n_1 + 2n_2 + 3n_3 = 0 \\ 2n_1 - 6n_2 + 6n_3 = 0 \Rightarrow n_i^{(1)} = \begin{bmatrix} 3 \\ 6 \\ 3n_1 + 6n_2 - 9n_3 = 0 \end{cases}$$

Similarly, we obtain:

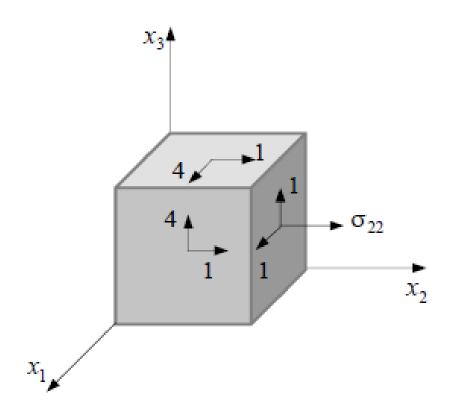
$$\mathbf{n}_{i}^{(2)} = \begin{bmatrix} -2\\1\\0 \end{bmatrix}; \ \mathbf{n}_{i}^{(3)} = \begin{bmatrix} 1\\2\\-3 \end{bmatrix}$$

Normalization of the principal directions:

$$\hat{\mathbf{n}}_{i}^{(1)} = \frac{\mathbf{n}_{i}^{(1)}}{\left\|\vec{\mathbf{n}}^{(1)}\right\|} = \frac{1}{\sqrt{70}} \begin{bmatrix} 3\\6\\5 \end{bmatrix} \quad ; \quad \hat{\mathbf{n}}_{i}^{(2)} = \frac{\mathbf{n}_{i}^{(2)}}{\left\|\vec{\mathbf{n}}^{(2)}\right\|} = \frac{1}{\sqrt{5}} \begin{bmatrix} -2\\1\\0 \end{bmatrix} \quad ; \quad \hat{\mathbf{n}}_{i}^{(3)} = \frac{\mathbf{n}_{i}^{(3)}}{\left\|\vec{\mathbf{n}}^{(3)}\right\|} = \frac{1}{\sqrt{14}} \begin{bmatrix} 1\\2\\-3 \end{bmatrix}$$

#### Problem 3:

The stress state at one point P of the continuous medium is given schematically by:



Obtain the value of the component  $\sigma_{22}$  of the Cauchy stress tensor such that there is at least one plane passing through P in which is free of stress;

Obtain the direction of the plane.

We seek to find a plane whose direction is  $\hat{\bf n}$  such that  $\hat{\bf t}^{(\hat{\bf n})} = \hat{\bf 0}$ . We can relate the Cauchy stress tensor to the traction vector by means of the equation:

$$\vec{t}^{(\hat{n})} = \sigma \cdot \hat{n}$$

thus:

$$\begin{bmatrix} t_1^{(\hat{\mathbf{n}})} \\ t_2^{(\hat{\mathbf{n}})} \\ t_3^{(\hat{\mathbf{n}})} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 4 \\ 1 & \sigma_{22} & 1 \\ 4 & 1 & 0 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Resulting in the following system of equations:

$$\begin{cases} n_2 + 4n_3 = 0 \Rightarrow n_3 = -\frac{1}{4}n_2 \\ n_1 + \sigma_{22}n_2 + n_3 = 0 \\ 4n_1 + n_2 = 0 \Rightarrow n_1 = -\frac{1}{4}n_2 \end{cases}$$

#### Problem 3:

#### Salution.

By combining the above equations we obtain:

$$n_1 + \sigma_{22}n_2 + n_3 = 0$$
  $\Rightarrow$   $-\frac{1}{4}n_2 + \sigma_{22}n_2 - \frac{1}{4}n_2 = 0$ 

$$\left(-\frac{1}{4} + \sigma_{22} - \frac{1}{4}\right) n_2 = 0$$

Then, for 
$$\vec{\mathbf{n}} \neq \vec{\mathbf{0}}$$
, we have:  $\left(-\frac{1}{4} + \sigma_{22} - \frac{1}{4}\right) = 0 \Rightarrow \sigma_{22} = \frac{1}{2}$ .

To determine the direction of the plane we start by the restriction  $n_i n_j = 1$ , then:

$$n_{i}n_{i} = 1$$
  $\therefore$   $n_{1}^{2} + n_{2}^{2} + n_{3}^{2} = 1$   

$$\Rightarrow \left(-\frac{1}{4}n_{2}\right)^{2} + n_{2}^{2} + \left(-\frac{1}{4}n_{2}\right)^{2} = 1$$
  

$$\Rightarrow n_{2} = \frac{2\sqrt{2}}{3} \quad ; \quad n_{1} = n_{3} = \frac{\sqrt{2}}{6}$$

Thus, the direction of the normal to the plane, when it meets  $\vec{t}^{\,(\hat{n})} = \vec{0}$ :

$$\hat{\mathbf{n}}_i = \frac{\sqrt{2}}{6} \begin{vmatrix} -1 \\ 4 \\ -1 \end{vmatrix}$$

### Problem 4:

&

If the state of stress at a point in a body is given as follows. Determine the components of the body force in order to satisfy the equations of equilibrium.

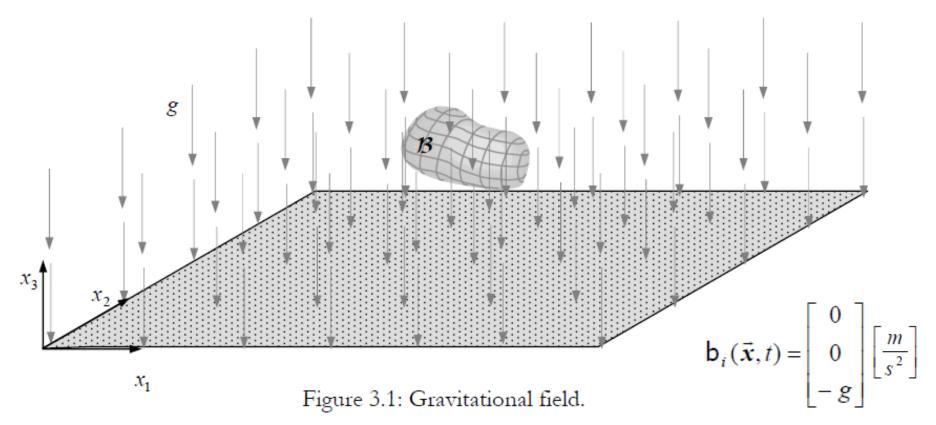
$$\sigma_x = 20x^3 + y^2$$
;  $\sigma_y = 30x^3 + 100$ ;;  $\sigma_z = 10(y^2 + z^2)$ 

$$\tau_{xy} = z$$
;  $\tau_{yz} = x^3$ ;  $\tau_{zx} = y^3$ 

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### Problem 5:

Ignoring the curvature of the Earth's surface, the gravitational field can be assumed to be uniform as shown in Figure 3.1, where g is the acceleration caused by gravity (the gravity of the Earth). Find the resultant force acting on the body  $\mathcal{B}$ .



All bodies immersed in a force field are subjected to the body force **b** 

## Problem 5: solution:

All bodies immersed in a force field are subjected to the body force **b** 

$$\mathbf{b}_{i}(\vec{x},t) = \begin{bmatrix} 0 \\ 0 \\ -g \end{bmatrix} \begin{bmatrix} \frac{m}{s^{2}} \end{bmatrix}$$

Hence, the total force acting on the body can be evaluated as follows:

$$\mathsf{F}_{i} = \int_{V} \rho \mathsf{b}_{i}(\vec{x}, t) \, dV = \begin{bmatrix} 0 \\ 0 \\ -\int_{V} \rho \, \mathsf{g} \, dV \end{bmatrix}$$

We can also verify the F unit:  $[F] = \int_V \left[ \frac{kg}{m^3} \right] \left[ \frac{m}{s^2} \right] \underbrace{\frac{[m^3]}{dV}} = \frac{kg \ m}{s^2} = N(Newton)$ .

#### Problem 6:

Given the tensor components:

$$\mathsf{T}_{ij} = \begin{bmatrix} 5 & 3 & 3 \\ 2 & 6 & 3 \\ 2 & 2 & 4 \end{bmatrix}$$

- a) Obtain the principal invariants of T, i.e. obtain I<sub>T</sub>, I<sub>T</sub> and II<sub>T</sub>;
- b) Obtain the characteristic polynomial associated with **T**;
- c) If  $\lambda_1$ ,  $\lambda_2$  y  $\lambda_3$  are the eigenvalues of  $\mathbf{T}$  and  $\lambda_1 = 10$ . Obtain  $\lambda_2$  and  $\lambda_3 > 2$ .

a) The principal invariants of T are:

$$I_T = Tr(T) = 5 + 6 + 4 = 15$$

$$II_T = \begin{vmatrix} 6 & 3 \\ 2 & 4 \end{vmatrix} + \begin{vmatrix} 5 & 3 \\ 2 & 4 \end{vmatrix} + \begin{vmatrix} 5 & 3 \\ 2 & 6 \end{vmatrix} = 56$$

$$\mathbf{III}_{\mathsf{T}} = \det(\mathsf{T}) = 60$$

b) The characteristic polynomial can be obtained by solving the determinant:

$$\begin{vmatrix} 5-\lambda & 3 & 3 \\ 2 & 6-\lambda & 3 \\ 2 & 2 & 4-\lambda \end{vmatrix} = 0 \implies \lambda^3 - \lambda^2 I_T + \lambda II_T - III_T = 0$$

thus:

$$\lambda^3 - 15\lambda^2 + 56\lambda - 60 = 0$$

c) In the principal space the following is true:

$$T'_{ij} = \begin{bmatrix} \lambda_1 = 10 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 > 2 \end{bmatrix}$$

where the principal invariants are

$$I_T = Tr(T) = \lambda_1 + \lambda_2 + \lambda_3 = 15$$
  $\Rightarrow \lambda_2 + \lambda_3 = 5$   
 $II_T = det(T) = \lambda_1 \lambda_2 \lambda_3 = 60$   $\Rightarrow \lambda_2 \lambda_3 = 6$ 

By combining these two equations we obtain:

We discard the solution  $\lambda_3^{(2)} = 2$ , thus  $\lambda_3 = 3$ . Then:

$$\mathsf{T}'_{ij} = \begin{bmatrix} 10 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

In this space we can check that 
$$\begin{cases} I_{\rm T} = {\rm Tr}({\bf T}) = 10 + 2 + 3 = 15 \\ II_{\rm T} = 2 \times 3 + 10 \times 3 + 10 \times 2 = 56 \\ III_{\rm T} = {\rm det}({\bf T}) = 10 \times 2 \times 3 = 60 \end{cases}$$

### Problem 7:

Find the principal values and directions of the second-order tensor **T**, where the Cartesian components of **T** are:

$$(\mathbf{T})_{ij} = \mathbf{T}_{ij} = \mathcal{T} = \begin{bmatrix} 3 & -1 & 0 \\ -1 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Solution: We need to find nontrivial solutions for  $(T_{ij} - \lambda \delta_{ij})\hat{n}_j = 0_i$ , which are constrained by  $\hat{n}_j \hat{n}_j = 1$  (unit vector). As we have seen, the nontrivial solution requires that:

$$T_{ij} - \lambda \delta_{ij} = 0$$

Explicitly, the above equation is:

$$\begin{bmatrix} T_{11} - \lambda & T_{12} & T_{13} \\ T_{21} & T_{22} - \lambda & T_{23} \\ T_{31} & T_{32} & T_{33} - \lambda \end{bmatrix} = \begin{bmatrix} 3 - \lambda & -1 & 0 \\ -1 & 3 - \lambda & 0 \\ 0 & 0 & 1 - \lambda \end{bmatrix} = 0$$

Developing the above determinant, we can obtain the cubic equation:

$$(1-\lambda)[(3-\lambda)^2-1]=0$$
  
 $\lambda^3-7\lambda^2+14\lambda-8=0$ 

We could have obtained the characteristic equation directly in terms of invariants:

$$I_T = Tr(T_{ij}) = T_{ii} = T_{11} + T_{22} + T_{33} = 7$$

$$II_{T} = \frac{1}{2} \left( T_{ii} T_{jj} - T_{ij} T_{ij} \right) = \begin{vmatrix} T_{22} & T_{23} \\ T_{32} & T_{33} \end{vmatrix} + \begin{vmatrix} T_{11} & T_{13} \\ T_{31} & T_{33} \end{vmatrix} + \begin{vmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{vmatrix} = 14$$

$$\mathbf{III}_{\mathsf{T}} = |\mathsf{T}_{ij}| = \epsilon_{ijk} \mathsf{T}_{i1} \mathsf{T}_{j2} \mathsf{T}_{k3} = 8$$

Then, the characteristic equation becomes:

$$\lambda^3 - \lambda^2 I_T + \lambda II_T - III_T = 0 \rightarrow \lambda^3 - 7\lambda^2 + 14\lambda - 8 = 0$$

On solving the cubic equation we obtain three real roots, namely:

$$\lambda_1 = 1;$$
  $\lambda_2 = 2;$   $\lambda_3 = 4$ 

We can also verify that:

$$I_T = \lambda_1 + \lambda_2 + \lambda_3 = 1 + 2 + 4 = 7$$

$$I_T = \lambda_1 \lambda_2 + \lambda_2 \lambda_3 + \lambda_3 \lambda_1 = 1 \times 2 + 2 \times 4 + 4 \times 1 = 14$$

$$I_T = \lambda_1 \lambda_2 \lambda_3 = 8$$

Thus, we can see that the invariants are the same as those evaluated previously.

#### Principal directions:

Each eigenvalue,  $\lambda_i$ , is associated with a corresponding eigenvector,  $\hat{\mathbf{n}}^{(i)}$ . We can use the equation  $(T_{ij} - \lambda \delta_{ij}) \hat{\mathbf{n}}_j = 0_i$  to obtain the principal directions.

$$\lambda_1 = 1$$

$$\begin{bmatrix} 3-\lambda_1 & -1 & 0 \\ -1 & 3-\lambda_1 & 0 \\ 0 & 0 & 1-\lambda_1 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 3-1 & -1 & 0 \\ -1 & 3-1 & 0 \\ 0 & 0 & 1-1 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

These become the following system of equations:

$$\begin{cases}
2n_1 - n_2 = 0 \\
-n_1 + 2n_2 = 0
\end{cases} \Rightarrow n_1 = n_2 = 0$$

$$\begin{cases}
0n_3 = 0 \\
n_i n_i = n_1^2 + n_2^2 + n_3^2 = 1
\end{cases}$$

Then we can conclude that:  $\lambda_1 = 1 \implies \hat{n}_i^{(1)} = [0 \ 0 \ \pm 1]$ .

**NOTE:** This solution could have been directly determined by the specific features of the T matrix. As the terms  $T_{13} = T_{23} = T_{31} = T_{32} = 0$  imply that  $T_{33} = 1$  is already a principal value, then, consequently, the original direction is a principal direction.

$$\lambda_2 = 2$$

$$\begin{bmatrix} 3 - \lambda_2 & -1 & 0 \\ -1 & 3 - \lambda_2 & 0 \\ 0 & 0 & 1 - \lambda_2 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 3 - 2 & -1 & 0 \\ -1 & 3 - 2 & 0 \\ 0 & 0 & 1 - 2 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
$$\begin{cases} n_1 - n_2 = 0 \Rightarrow n_1 = n_2 \\ -n_1 + n_2 = 0 \\ -n_3 = 0 \end{cases}$$

The first two equations are linearly dependent, after which we need an additional equation:

$$n_i n_i = n_1^2 + n_2^2 + n_3^2 = 1 \Rightarrow 2n_1^2 = 1 \Rightarrow n_1 = \pm \sqrt{\frac{1}{2}}$$

Thus:

$$\lambda_2 = 2$$
  $\Rightarrow$   $\hat{n}_i^{(2)} = \left[ \pm \sqrt{\frac{1}{2}} \pm \sqrt{\frac{1}{2}} \quad 0 \right]$ 

$$\lambda_3 = 4$$

$$\begin{bmatrix} 3 - \lambda_3 & -1 & 0 \\ -1 & 3 - \lambda_3 & 0 \\ 0 & 0 & 1 - \lambda_3 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 3 - 4 & -1 & 0 \\ -1 & 3 - 4 & 0 \\ 0 & 0 & 1 - 4 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} -n_1 - n_2 = 0 \\ -n_1 - n_2 = 0 \end{cases} \Rightarrow n_1 = -n_2$$

$$\begin{cases} -3n_3 = 0 \end{cases}$$

$$n_i n_i = n_1^2 + n_2^2 + n_3^2 = 1 \Rightarrow 2n_2^2 = 1 \Rightarrow n_2 = \pm \sqrt{\frac{1}{2}}$$

Then:

$$\lambda_3 = 4$$
  $\Rightarrow$   $\hat{\mathsf{n}}_i^{(3)} = \left[ \mp \sqrt{\frac{1}{2}} \pm \sqrt{\frac{1}{2}} \quad 0 \right]$ 

Afterwards, we summarize the eigenvalues and eigenvectors of T:

$$\lambda_1 = 1 \qquad \Rightarrow \hat{\mathsf{n}}_i^{(1)} = \begin{bmatrix} 0 & 0 & \pm 1 \end{bmatrix}$$

$$\lambda_2 = 2 \qquad \Rightarrow \hat{\mathsf{n}}_i^{(2)} = \begin{bmatrix} \pm \sqrt{\frac{1}{2}} & \pm \sqrt{\frac{1}{2}} & 0 \end{bmatrix}$$

$$\lambda_3 = 4 \qquad \Rightarrow \hat{\mathsf{n}}_i^{(3)} = \begin{bmatrix} \mp \sqrt{\frac{1}{2}} & \pm \sqrt{\frac{1}{2}} & 0 \end{bmatrix}$$

NOTE: The tensor components of this problem are the same as those used in Problem 1.62. Additionally, we can verify that the eigenvectors make up the transformation matrix, A, between the original system,  $(x_1, x_2, x_3)$ , and the principal space,  $(x'_1, x'_2, x'_3)$ , (see Problem 1.62).

### Problem 8:

Given a body in equilibrium in which the Cauchy stress tensor field is represented by its components:

$$\sigma_{11} = 6x_1^3 + x_2^2$$
;  $\sigma_{12} = x_3^2$   
 $\sigma_{22} = 12x_1^3 + 60$ ;  $\sigma_{23} = x_2$   
 $\sigma_{33} = 18x_2^3 + 6x_3^3$ ;  $\sigma_{31} = x_1^2$ 

Obtain the body force vector (per unit volume) at the point  $(x_1 = 2; x_2 = 4; x_3 = 2)$ .

The equilibrium equations:

$$\nabla \cdot \cdot \boldsymbol{\sigma} + \rho \vec{\mathbf{b}} = \vec{\mathbf{0}}$$

$$\begin{cases}
\frac{\partial \sigma_{11}}{\partial x_1} + \frac{\partial \sigma_{12}}{\partial x_2} + \frac{\partial \sigma_{13}}{\partial x_3} + \rho b_1 = 0 \Rightarrow \rho b_1 = -\frac{\partial \sigma_{11}}{\partial x_1} - \frac{\partial \sigma_{12}}{\partial x_2} - \frac{\partial \sigma_{13}}{\partial x_3} \\
\frac{\partial \sigma_{21}}{\partial x_1} + \frac{\partial \sigma_{22}}{\partial x_2} + \frac{\partial \sigma_{23}}{\partial x_3} + \rho b_2 = 0 \Rightarrow \rho b_2 = -\frac{\partial \sigma_{21}}{\partial x_1} - \frac{\partial \sigma_{22}}{\partial x_2} - \frac{\partial \sigma_{23}}{\partial x_3} \\
\frac{\partial \sigma_{31}}{\partial x_1} + \frac{\partial \sigma_{32}}{\partial x_2} + \frac{\partial \sigma_{33}}{\partial x_3} + \rho b_3 = 0 \Rightarrow \rho b_3 = -\frac{\partial \sigma_{31}}{\partial x_1} - \frac{\partial \sigma_{32}}{\partial x_2} - \frac{\partial \sigma_{33}}{\partial x_3} \\
\begin{pmatrix} \rho b_1 = -18x_1^2 - 0 - 0 \\ \rho b_2 = -0 - 0 - 0 & \Rightarrow \rho b_i = \begin{pmatrix} -18x_1^2 \\ 0 \\ -2x_1 - 1 - 18x_2^2 \end{pmatrix} \\
\end{pmatrix}$$

At the point  $x_1 = 2$ ;  $x_2 = 4$ ;  $x_3 = 2$  we obtain:

$$\rho b_i = \begin{bmatrix} -72 \\ 0 \\ -77 \end{bmatrix}$$
 (Force per unit volume)